



DVC Family

Intella™

Programming

Variable Guide



Introduction

Program variables are storage locations in memory with unique identifiers which contain values that are paired with specific application functions. Program variables may represent the configuration or state of an input or output, a defined variable created by the programmer, an EEMEM location or storage space for J1939 data etc. Most application variables are open to control by the programmer, while certain variables while available for testing (mainly used for module configuration) should not be manipulated by the application program.

For More information, please consult the DVC710 Family System and Programming Guide available on our website, <http://hctcontrols.com/>.

Program Variables by Function

| Miscellaneous Variables | | |
|---|---|--|
| Name | Description | Range |
| Supply ⁽¹⁾ | The Power Supply voltage. The value returned is in units of supply volts (sv) | |
| DVC_Temperature ⁽¹⁾ | Internal DVC710 controller temperature. The value returned is in units of °C + 40. Therefore, – 40°C is returned as 0. | |
| FreeRunningTimer | 16 bit counter that continually increments every 100 micro seconds. Counts from 0 to 65535 (6.5 seconds) then begins again. Could be used to track timing between two events. | |
| MACID | This variable returns the MACID of the DVC controller. | |
| HC_Coil_Gain_OG1 ⁽¹⁾ HC_Coil_Gain_OG2 ⁽¹⁾ HC_Coil_Gain_OG3 ⁽¹⁾ | Coil gain constant used by the BIOS to determine actual coil current from A/D values derived by the controller's current feedback circuits. Max_cur = (current_in_ma * 100) / HC Coil Gain OG1 | 0 to 1023 |
| LC_Coil_Gain_OG1 ^(1,3) LC_Coil_Gain_OG2 ^(1,3) LC_Coil_Gain_OG3 ^(1,3) | Same as above for Low Current application, (90mA or less Max Current) | 0 to 1023 |
| BlinkCode | Commands the Status LED. | 0 to 65535 – DVC707 0 to 999 – DVC710 |



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| Universal and Analog Inputs | | |
|------------------------------------|--|--|
| Name | Description | Range |
| Name | Name of input | 0% to 100% (0 – 1023) |
| Name.Dir | Inputs direction bit | False (Lower Side), True (Upper Side) |
| Name.RawVolts | Volts or Milliamps | 0 to 1023 * Scale ⁽²⁾ |
| Name.RampVolts | Ramped Volts = RampVolts * Scale Factor | 0 to 1023 * Scale ⁽²⁾ |
| Name.MinVolts | Name = 0% (i.e. Center not enabled) | 0 to 1023 * Scale ⁽²⁾ |
| Name.MaxVolts | Name = 100% | 0 to 1023 * Scale ⁽²⁾ |
| Name.MinLimit | Threshold for Name.MinF | 0 to 1023 * Scale ⁽²⁾ |
| Name.MaxLimit | Threshold for Name.MaxF | 0 to 1023 * Scale ⁽²⁾ |
| Name.RefMinLimit | Threshold for Name.MinRF | 0 to 1023 * Scale ⁽²⁾ |
| Name.RefMaxLimit | Threshold for Name.MaxRF | 0 to 1023 * Scale ⁽²⁾ |
| Name.CenterVolts | Set Point for Center Volts | 0 to 1023 * Scale ⁽²⁾ |
| Name.Deadbandv | Plus and minus volts about CenterVolts | 0 to 1023 * Scale ⁽²⁾ |
| Name.MinF | Set when Input Voltage is less than Min Limit | False (ok), True (Outside Limit) |
| Name.MaxF | Set when Input Voltage is greater than Max Limit | Range: False (ok), True (Outside Limit) |
| Name.LOS | Set after time out. For Universal Pulse inputs Only | False (Pulses ok), True (No Pulse Input) |
| Name.RealRPM | The Unsigned Integer Value of the RPM. For Universal Pulse inputs Only | 0 to 9999 |
| Name.Counter | Value of the Counter. Universal Pulse inputs Only | 0 to 65535 |
| Name.PulsesPerRev | Pulses Per Revolution RPM inputs only. | 0 to 9999 |



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| Digital Inputs | | |
|----------------------------------|--|--|
| Name | Description | Range |
| Name | Name of the switch | False or Off, True or On |
| Name.RealRPM ⁽³⁾ | The Unsigned Integer Value of the RPM. | 0 to 9999 |
| Name.PulseTimeout ⁽³⁾ | Get/Set Pulse Timeout for Loss of Signal | 0 to 65535 |
| Name.PulsesPerRev ⁽³⁾ | Get/Set Pulses Per Revolution | 0 to 9999 |
| Name.Counter ⁽³⁾ | Get/Set Unsigned Integer Value of the Counter. Pulse inputs Only | 0 to 65535 |
| Name.LOS ⁽³⁾ | Loss of Signal flag set after time out. For Pulse inputs Only | False (Pulses ok), True (No Pulse Input) |

| I / O Function Variables | | |
|---------------------------------|-------------------------------------|-----------------------|
| Name | Description | Range |
| Name.In | The Input of the Transfer Function | 0% to 100% (0 – 1023) |
| Name.Out | The Output of the Transfer Function | 0% to 100% (0 – 1023) |
| Name.X0 | The X0 of the input/output function | 0% to 100% (0 – 1023) |
| Name.X1 | The X1 of the input/output function | 0% to 100% (0 – 1023) |
| Name.X2 | The X2 of the input/output function | 0% to 100% (0 – 1023) |
| Name.X3 | The X3 of the input/output function | 0% to 100% (0 – 1023) |
| Name.X4 | The X4 of the input/output function | 0% to 100% (0 – 1023) |
| Name.X5 | The X5 of the input/output function | 0% to 100% (0 – 1023) |
| Name.X6 | The X6 of the input/output function | 0% to 100% (0 – 1023) |
| Name.X7 | The X7 of the input/output function | 0% to 100% (0 – 1023) |
| Name.Y0 | The Y0 of the input/output function | 0% to 100% (0 – 1023) |
| Name.Y1 | The Y1 of the input/output function | 0% to 100% (0 – 1023) |
| Name.Y2 | The Y2 of the input/output function | 0% to 100% (0 – 1023) |
| Name.Y3 | The Y3 of the input/output function | 0% to 100% (0 – 1023) |
| Name.Y4 | The Y4 of the input/output function | 0% to 100% (0 – 1023) |
| Name.Y5 | The Y5 of the input/output function | 0% to 100% (0 – 1023) |
| Name.Y6 | The Y6 of the input/output function | 0% to 100% (0 – 1023) |
| Name.Y7 | The Y7 of the input/output function | 0% to 100% (0 – 1023) |



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Outputs Dual Coil High Side

| Name | Description | Range |
|----------------------|---|---------------------------------------|
| Name | Name for the PWM Output | 0% to 100% (0 – 1023) |
| Name.Dir | PWM Outputs direction bit | False (Lower Side), True (Upper Side) |
| Name.Enable | PWM Outputs enable bit | True [PWM Enabled], False [PWM = 0] |
| Name.Short | PWM Output Short Status Flag | Off [Coil Ok], On [Coil Short] |
| Name.Open | PWM Output Open Status Flag | Off [Coil Ok], On [Coil Open] |
| HSEven#Name.Rampup | Set the ramp up rate (time to travel from 0% to 100%) | 0.0 to 65.00 s |
| HSEven#Name.Rampdown | Set the ramp down rate (time to travel from 100% to 0%) | 0.0 to 65.00 s |
| HSEven#Name.Short | Get the Coil Flag for Short Status | Off [Coil Ok], On [Coil Short] |
| HSEven#Name.Open | Get the Coil Flag for Open Status | Off [Coil Ok], On [Coil Open] |
| HSOdd#Name.Rampdown | Set the ramp down rate (time to travel from 100% to 0%) | 0.0 to 65.00 s |
| HSOdd#Name.Short | Get the Coil Flag for Short Status | Off [Coil Ok], On [Coil Short] |
| HSOdd#Name.Open | Get the Coil Flag for Open Status | Off [Coil Ok], On [Coil Open] |
| Name.Cur | Current actual * CurGain = amps | 0 – 3.5 amps |
| Name.RampCur | Ramped Current*CurGain= amps | 0 – 3.5 amps |
| Name.CurErr | Current Error = RampCur – Cur | 16 bit signed integer |
| Name.CurSumErr | Current Error accumulated over time | 0 – 65535 |
| Name.CurP | Current Proportional Term Constant “P” | 0 – 255 ⁽⁴⁾ |
| Name.CurI | Current Proportional Term Constant “I” | 0 – 255 ⁽⁴⁾ |
| Name.MinCurA | Minimum Current Coil A *.001 = amps | 0 – 3.5 amps |
| Name.MaxCurA | Maximum Current Coil A *.001 = amps | 0 – 3.5 amps |
| Name.MinCurB | Minimum Current Coil B *.001 = amps | 0 – 3.5 amps |



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| Single Coil High Side / Single Coil Low Side | | |
|---|--|-------------------------------------|
| Name | Description | Range |
| (Low-Side/PWM) Name | Set or test the state Current Target or Process in percentage of min to max current 0 = 0 Current, .1% = Min Current, and 100% = Max Current | 0% to 100% (0 – 1023) |
| Name.Enable | Set the PWM to 0 or enable the PWM | True [PWM Enabled], False [PWM = 0] |
| Name.Short | Get the Coil Flag for Short Status | Off [Coil Ok], On [Coil Short] |
| Name.Open | Get the Coil Flag for Open Status | Off [Coil Ok], On [Coil Open] |
| Name.Rampup | Set the ramp up rate (time to travel from 0% to 100%) | 0.0 to 65.00 s |
| Name.Rampdown | Set the ramp down rate (time to travel from 100% to 0%) | 0.0 to 65.00 s |
| Name.Frequency | Set PWM frequency | 0 to 1000 for 0 to 100hz |
| Name.Dutycycle | Set PWM duty cycle | 0 to 1023 for 0 to 100% |
| Name.Freqerror | Returns error 0 = No Error 1 = Frequency error, 2 means duty cycle error | |
| HSEvenName ⁽⁵⁾ | Set the Bang-bang Coil to On or Off | Off, On |
| HSEven#Name.Short | Get the Coil Flag for Short Status | Off [Coil Ok], On [Coil Short] |
| HSEven#Name.Open | Get the Coil Flag for Open Status | Off [Coil Ok], On [Coil Open] |
| HSOddName ⁽⁶⁾ | Set the Bang-bang Coil to On or Off | Off, On |
| HSOdd#Name.OpenDisable | Set the Disable Coil Open Detection | 0 [Enabled], 1 [Disabled] |
| HSOdd#Name.Short | Get the Coil Flag for Short Status | Off [Coil Ok], On [Coil Short] |
| HSOdd#Name.Open | Get/Set the Coil Flag for Open Status | Off [Coil Ok], On [Coil Open] |
| Name.Cur | Current actual * CurGain = amps | 0 – 3.5 amps |
| Name.RampCur | Current ramped Current*CurGain= amps | 0 – 3.5 amps |
| Name.CurErr | Current Error = RampCur – Cur | 16 Signed Integer |
| Name.CurSumErr | Current Error accumulated over time | 0 – 65535 |
| Name.CurP | Current Proportional Term Constant “P” | 0 – 255 ⁽⁴⁾ |
| Name.CurI | Current Proportional Term Constant “I” | 0 – 255 ⁽⁴⁾ |
| Name.MinCurA | Minimum Current Coil A *.001 = amps | 0 – 3.5 amps |
| Name.MaxCurA | Maximum Current Coil A *.001 = amps | 0 – 3.5 amps |



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High Side Only

| Name | Description | Range |
|-------------------------|--|--------------------------------|
| HSEvenName | Set/Get the state of the Output | Off, On |
| HSEven#Name.OpenDisable | Set the Disable the Outputs Open Detection Feature | 0 [Enabled], 1 [Disabled] |
| HSEven#Name.Short | Get the Coil Flag for Short Status | Off [Coil Ok], On [Coil Short] |
| HSEven#Name.Open | Get the Coil Flag for Open Status | Off [Coil Ok], On [Coil Open] |
| HSOddName | Set/Get the state of the Output | Off, On |
| HSOdd#Name.OpenDisable | Set the Disable the Outputs Open Detection Feature | 0 [Enabled], 1 [Disabled] |

Process PI Variables

| Name | Description | Range |
|----------------|---|------------------------|
| Name.Setpoint | The desired % set point position for the output | 0 to 100% (0 – 1023) |
| Name.Feedback | The % feedback position for the output | 0 to 100% (0 – 1023) |
| Name.ProErr | Error = Set point – Feedback | 16 bit signed integer |
| Name.ProSumErr | Error accumulated over time | 0 – 65535 |
| Name.ProP | Process Proportional Term Constant “P” | 0 – 255 ⁽⁴⁾ |
| Name.ProI | Process Proportional Term Constant “I” | 0 – 255 ⁽⁴⁾ |
| Name.ProItime | Update / Integration Time | 0.0 to 650.00 s |
| Name.Cur | Current actual * CurGain = amps | 0 – 3.5 amps |
| Name.RampCur | Current ramped Current*CurGain= amps | 0 – 3.5 amps |
| Name.CurErr | Current Error = RampCur – Cur | 16 bit signed integer |
| Name.CurSumErr | Current Error accumulated over time | 0 – 65535 |
| Name.CurP | Current Proportional Term Constant “P” | 0 – 255 ⁽⁴⁾ |
| Name.CurI | Current Proportional Term Constant “I” | 0 – 255 ⁽⁴⁾ |
| Name.MinCurA | Minimum Current Coil A *.001 = amps | 0 – 3.5 amps |
| Name.MaxCurA | Maximum Current Coil A *.001 = amps | 0 – 3.5 amps |



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NOTES:

- 1 Read Only; Do not try to set these variables.
- 2 Scale depends on Input Range (0 to 5 = .00489, 0 to 10 = .00977, 0 to 25ma = 0.02158)
- 3 DVC707 Only.
- 4 Recommend range; 0 – 64. (do not exceed 64)
- 5 Available in; Single Coil High Side Mode, Single Coil Low Side Mode and High Side Only Mode. Otherwise, Read Only.
- 6 Available in; Single Coil Low Side Mode and High Side Only Mode. Otherwise, Read Only.